

# Quick Start Guide

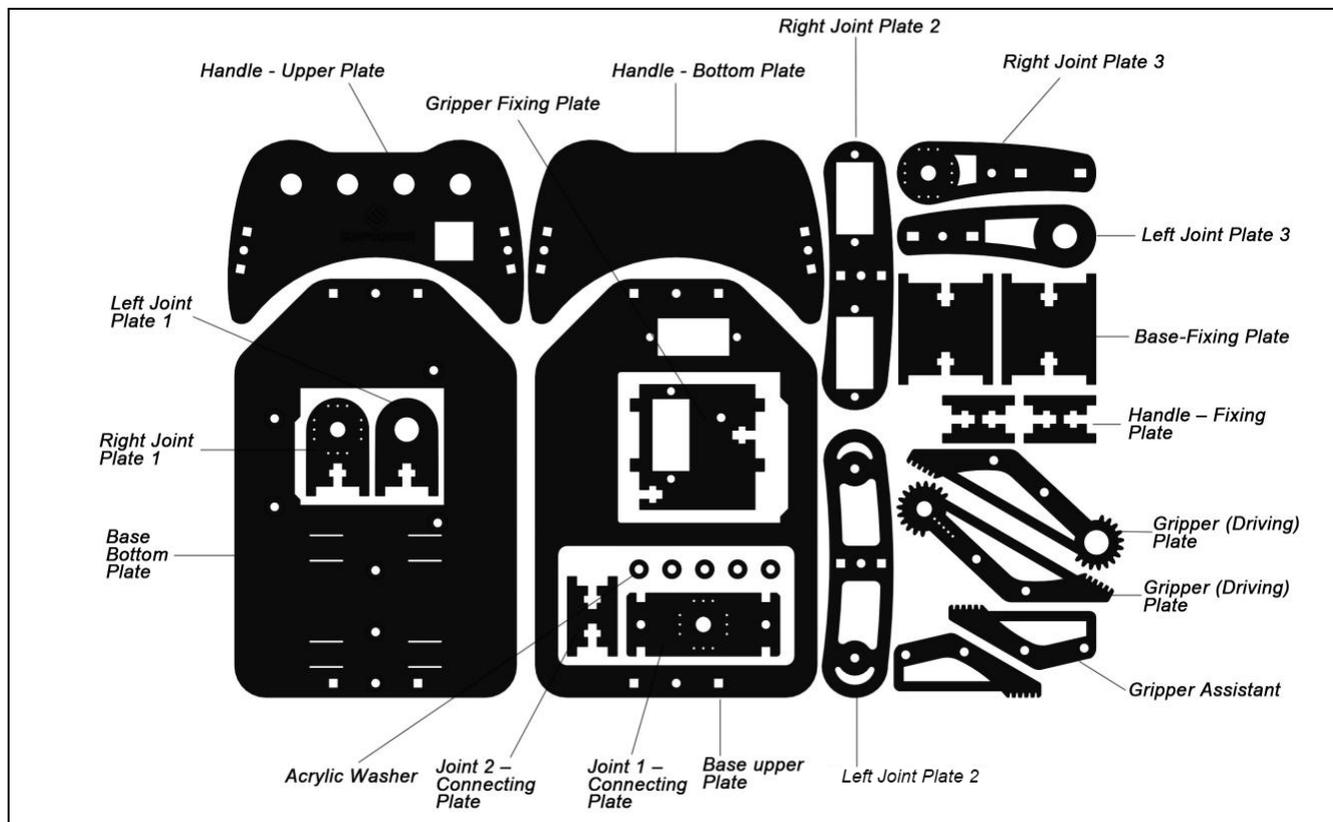
Model RBA18

Robot Arm Kit for Arduino-Rollarm

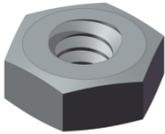


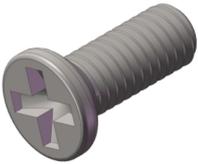
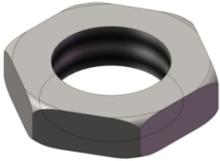
# Components List

## 1. Acrylic Plates



## 2. Connecting Components

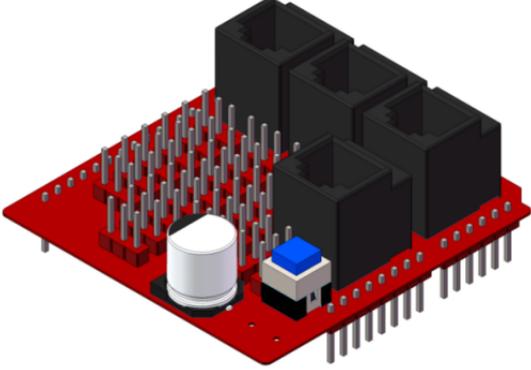
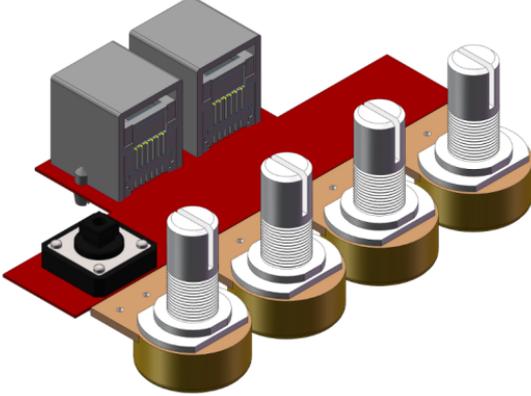
Name	Component	Qty.
M1.2*4 Self-Tapping Screw		14
M2*8 Screw		8
M2 Nut		8

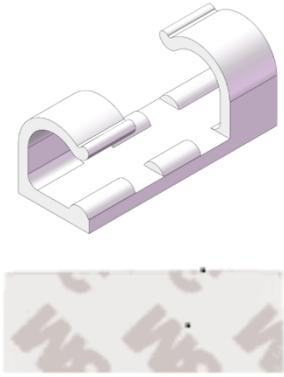
M3*8 Flat-Head Screw		2
M3*8 Screw		10
M3*10 Screw		18
M3 Nut		20
M7 Thin Nut		4
M3*10*1 Washer		1
M3*10 Aluminium Tube		5
M3*6 Corn Rivet		2

<p>φ3*φ8*4 Band Edge Bearing</p>		<p>3</p>
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### 3. Electronic Components

<p>SunFounder Servo (9g)</p>		<p>2</p>
<p>DXW 90 Servo (9g)</p>		<p>2</p>
<p>Potentiometer Button</p>		<p>4</p>
<p>Push Button</p>		<p>1</p>
<p>2*18650 Battery Holder</p>		<p>1</p>

<p>SunFounder UNO</p>		<p>1</p>
<p>Expansion Board</p>		<p>1</p>
<p>Potentiometer Module</p>		<p>1</p>
<p>USB Cable (UNO)</p>		<p>1</p>
<p>RJ11 Cable</p>		<p>2</p>
<p>Ribbon</p>		<p>1</p>
<p>3M Non-skid Pad</p>		<p>4</p>

Heat Sink Tubing		2
Cable Clip		2

#### 4. Tools

Screwdriver		1
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#### 5. Batteries

18650 Battery		2
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#### 6. Battery Charger

Battery Charger UL Approved		1
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## Resources

1. **Download and install the Arduino IDE for your system from here:**

<https://www.arduino.cc/en/Main/Software>

2. **To download the programs that run on Arduino for the Robo-Arm, go to**

[http://v3.hamiltonbuhl.com/uploads/roboarm/DIY\\_Control\\_Robot\\_Arm\\_kit\\_for\\_Arduino-Rollarm.zip](http://v3.hamiltonbuhl.com/uploads/roboarm/DIY_Control_Robot_Arm_kit_for_Arduino-Rollarm.zip)

- Download the zip file to your local hard drive and open.
- Reference the detailed instructions when you install these files.
- For a complete set of instructions, go to the Instructions folder and open the PDF or watch the video (see links below)
- Each program below should be uploaded separately when your robot is ready to program for each function.

**Inside the folder you will see:**

### **DIY\_Control\_Robot\_Arm\_kit\_for\_Arduino-Rollarm**

#### **a. ArduinoCode Folder:**

- [Arduino Code/Servo/Servo.ino](#) is the installer for powering the servos
- [Arduino Code/LIFA\\_Base /LIFA\\_Base.ino](#) is the communication between Labview Software and Arduino
- [Rollarm/Rollarm.ino](#) is the control for servos and has three sub-programs that will open automatically when you open the main program: Rollarm.ino.

**b. Instructions Folder:** Contains the full Instruction Manual for RoboArm

**c. Schematic Folder:** Contains diagrams for board set up.

3. **Labview software to control the robot from your PC can be found here:**

<http://v3.hamiltonbuhl.com/uploads/roboarm/Labview.zip>

Double-click the setup.exe file to install.

4. **Below are links to helpful instructional and installation videos:**

<http://v3.hamiltonbuhl.com/uploads/roboarm/videos/RoboArm-Part1.mp4>

<http://v3.hamiltonbuhl.com/uploads/roboarm/videos/RoboArm-Part2.mp4>

## **One Year Warranty**

Warranty begins the date item ships from our warehouse. All products have a one-year warranty from original date of shipment, unless otherwise noted.



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